Spectrum-based Fault Localization: A Pair Scoring Approach

Patrick Daniel and Kwan Yong Sim

Faculty of Engineering, Computing and Science, Swinburne University of Technology Kuching, Sarawak, Malaysia E-mail: pdaniel_koe@yahoo.com; ksim@swinburne.edu.my

*Abstract—***Spectrum-based Fault Localization (SBFL) is a popular fault localization technique that ranks statements in a program according to their suspiciousness to be faulty based on the statement execution records (spectra) of pass and fail test cases. Many SBFL metrics have been proposed with varying accuracies in ranking of faulty statement. In this paper we proposed a new SBFL metric based on a pair scoring approach. We evaluated the performance of the proposed metric and compare it with other existing SBFL metrics. Despite its simplicity, we found the proposed metric outperformed majority of the existing SBFL metrics.**

*Index Terms—***Software Engineering, Software Testing, Debugging, Spectrum-based Fault Localization**

I. INTRODUCTION

Software testing and debugging are the most expensive but necessary activity in software development life cycle for software quality assurance [1] and [2]. In the software development process, faulty statement in software code may lead the software failures such as crash or incorrect outputs and results. The task to determine and find the faulty statement is called fault localization. In a software system with thousands of lines of code, it will be very time consuming for the software developer to locate the faulty statement. Researchers in software debugging have designed effective ways to find the fault statement through fault localization approaches.

One of the popular in software debugging approaches is Spectrum-based Fault Localization (SBFL) [3]-[8]. In SBFL, the statement execution record (spectra) of pass and fail test cases are analyzed to assist software developer to locate the faulty statement. SBFL metrics have been formulated to rank the statements in software code according to their likeliness to be the faulty statement. In SBFL, statement with the highest score calculated by the SBFL metric will be ranked first for inspection as it is the most suspected statement that might be the faulty statement. On the other hand, the statement with the lowest score is the safest statement as it is most unlikely to be the faulty statement. Through this ranking, software developer can inspect the top ranking statement first to locate the faulty statement rather than checking statement by statement from the beginning until the end of the software code.

The performance of SBFL metric is measured by how fast it leads software developer to the faulty statement. This is determined by how high it ranks the faulty statement based on the score calculated from the SBFL metric. Every SBFL metric is designed differently to rank the suspected statement. This makes every SBFL metric unique and has different capability in fault localization.

In this paper we propose a new SBFL metric named *pair scoring*. This technique works by comparing the execution paths of a pair of pass and fail test cases and assign score to each statement according to its likeliness to be the faulty statement. All possible combinations of pass and fail test cases are paired for scoring and the total score for each statement is used to rank the statement for its likeliness to be faulty. We evaluated the performance of the proposed metric on real life software artifacts and compare it with other existing SBFL metrics. Despite its simplicity, we found the proposed metric outperformed majority of the existing SBFL metrics.

The remaining of this paper is organized as follow: Section II outlines the preliminaries of Spectra-based Fault Localization (SBFL), the test objected used and the existing SBFL metrics studied in this paper for comparison with the proposed SBFL metric. The new SBFL is presented in Section III. Section IV describes the experiments conducted to evaluate the performance of the proposed metric and compares it with other existing SBFL metrics. Section V discusses the findings and Section VI concludes the paper.

II. PRELIMINARIES

Program spectra refer to information about statement executions by test cases. Four common coefficients are computed as the spectrum for each statement. These coefficients are *aef*, *anf*, *aep*, and *anp*. The first coefficient, *aef*, represents the number of fail test cases that have executed the statement, whereas the second coefficient, *anf*, represents the number of fail test cases that have not executed the statement. Similarly, the third coefficient, *aep*, represents the number of pass test cases that have executed the statement (as illustrated in Fig. 1), whereas the last coefficient, *anp*, represents the number of pass test cases that have not executed the statement. Intuitively, a faulty statement will have high values for *aef* and *anp* and low values for *anf* and *aep*.

-

Manuscript received June 25, 2013; revised August 23, 2013.

Figure 1. Illustration of aef coefficient.

Based on coefficients *aef*, *anf*, *aep*, and *anp*, a SBFL metric is used to compute a score for every statement to rate its likeliness to be faulty. The statements are then ranked from the highest score to the lowest score. To locate the faulty statement, a software developer will inspect the highest ranked statement first followed by the lower ranked statements until the faulty statement is located. Therefore, a good SBFL metric will rank faulty statement high so that only few statements need to be inspected before the faulty statement is successfully located. Hence the performance of a SBFL metric is commonly measured with the percentage of code inspected (*pci*) before the faulty statement is successfully located.

$$
pci = \frac{rank\ of\ faulty\ statement}{total\ number\ statement} \times 100\% \tag{1}
$$

A. Testing Subject

The programs in Siemens Test Suite have been selected as our subject programs to evaluate the performance of the new SBFL metric. Programs in Siemens Test Suite are commonly used to benchmark the performance of SBFL metrics [9]-[12]. It is downloadable from the Software Information Repository [13]. Siemens Test Suite contains seven programs. Each program has one original correct version and multiple faulty versions of the program. The test case execution scripts are included for each program. Table I shows the specifications of programs in Siemens Test Suite which include names of the programs, total faulty versions, total lines of code, number of test cases, description of the program, and list of the excluded versions.

In our experiment, all test cases will be executed for each program. We exclude print_tokens {v4, v6} because these versions are identical with the original correct version of the program, where no faulty statement exists. As we are focusing this study on single fault programs, print_tokens {v1}, replace {v21}, schedule {v2, v7}, and tcas {v10, v11, v15, v31, v32, v33, v40} are excluded because the multiple faulty statements exist in these versions. We also exclude print tokens ${v2}$, replace {v12}, tcas {v13, v14, v36, v38}, tot_info {v6, v10, v19, v21} where the faulty statement is a non-executable statement. In addition, some of the faulty versions do not produce any failure output even though faulty statement existed in program code. As a results, we exclude print_tokens2 {v10}, replace {v32}, and schedule2 {v9}. We use GCC version 4.6.1 Gcov(GNU-GCC), running on Ubuntu 11.10 to gather the spectra from Siemens Test Suite.

B. SBFL Metrics

Software debugging researchers have proposed various number of SBFL metrics [3], [14]-[16] to produce the best ranking for fault statement. The aim is to save software developers' time to locate the faulty statement in real life situation by inspecting as little statement as possible. Table II lists of existing SBFL metrics which are evaluated in this paper.

		TABLE II. SBFL METRICS					
Name	Formula	Name	Formula				
Naish1	$\begin{cases} -1 & \text{if } a\epsilon f < F \\ P - a e p & \text{if } a\epsilon f = F \end{cases}$	Zoltar	aet $\label{eq:1} aef + anf + aep + \frac{10000\overline{anfaep}}{2\overline{16}}$ aef				
Naish2	$aef - \frac{aep}{aep + anp + 1}$	Simple Matching	$aef + amp$ $aef + anf + aep + anp$				
Jaccard	aef \overline{a} ef + anf + \overline{a} ep	Sokal	$2(aef + amp)$ $2(aef + amp) + anf + aep$				
Anderberg	aef $\overline{aef + 2(anf + aep)}$	Rogers & Tanimoto	$aef + amp$ $\overline{aef + amp + 2(anf + aep)}$				
Sorensen- Dice	2aef $2aef + anf + aep$	Russel & Rao	aef $aef + anf + aep + anp$				
Dice	2aef $aef + anf + aep$	AMPLE	aef $\left \frac{aef}{aef + anf} - \frac{aep}{aep + anp}\right $				
qe	aef \overline{a} ef + \overline{a} ep	Tarantula	$\frac{aef}{aef + anf} / \left(\frac{aef}{aef + anf} + \frac{aep}{aep + anp} \right)$				
Wong1	aef	CBI Inc.	aef $aef + anf$ $\overline{aef + aep}$ $\overline{aef + anf + aep + anp}$				
Hamming etc.	$aef + amp$	Ochiai	aef $\sqrt{(aef + anf)(aef + aep)}$				
M1	$aef + amp$ $an f + aep$	M ₂	aef \overline{a} ef + anp + 2(anf + aep)				
Kulczynski1	aef $an f + aep$	AMPLE2	aef аер \overline{a} ef + anf aep + anp				
Binary	if $aef < F$ (0 ែ <i>if</i> $aef = F$	Euclid	$\sqrt{aef + anp}$				
Wong3			if $aep \leq 2$ aep $aef - h$, where $h = \begin{cases} aep & if \ aep \leq 2 \\ 2 + 0.1(aep - 2) & if \ 2 < aep \leq 10 \\ 2.8 + 0.001(aep - 10) & if \ aep > 10 \end{cases}$				
Ochiai2	aefanp $\sqrt{(aef + aep)(anp + anf)(aef + anf)(aep + anp)}$						
Arithmetic Mean	$2aefanp - 2anfaep$ $\overline{(aef + aep)(anp + anf) + (aef + anf)(aep + anp)}$						
Geometric Mean		$aefanp-anfaep$ $\sqrt{(aef + aep)(anp + anf)(aef + anf)(aep + anp)}$					
Harmonic Mean	$(aefanp - anfaep)((aef + aep)(anp + anf) + (aef + anf)(aep + anp)) \label{eq:1}$ $(aef + aep)(anp + anf)(aef + anf)(aep + anp)$						
Rogot2	$\frac{1}{4} \left(\frac{aef}{aef + aep} + \frac{aef}{aef + anf} + \frac{anp}{anp + aep} + \frac{anp}{anp + anf} \right)$						
Cohen	$2aefanp - 2anfaep$ $\overline{(aef + aep)(anp + aep) + (aef + anf)(anf + anp)}$						
III.	METHODOLOGY OF NEW SBFL METRIC The new SBFL metric is based on Pair Scoring, This technique works by assigning score to each statement based on the execution coverage of a pair of pass test case and fail test case. An example is shown in Fig. 2. Consider test case f and g for example. Scores are		statement is executed by f and g . The highest scor- given to the statement which is executed by fail tea but not executed by pass test case g because this contact combination to suggest that the statement is of h and is likely to be faulty. The lowest score (0) is a the statement which is executed only by pass test but not executed by fail test case f and also statement which is not executed by both f and				

TABLE II. SBFL METRICS

III. METHODOLOGY OF NEW SBFL METRIC

statement is executed by *f* and *g*. The highest score (2) is given to the statement which is executed by fail test case *f* but not executed by pass test case *g* because this coverage combination to suggest that the statement is of high risk and is likely to be faulty. The lowest score (0) is given to the statement which is executed only by pass test case *g* but not executed by fail test case *f* and also for the statement which is not executed by both *f* and *g*. An uncertain score (1) is given to statement which are

executed by both *f* and *g*. This pair scoring process is repeated for all possible paring combinations of pass test cases and fails test cases in the test suite. The sum of scores for each statement is then used to rank the statement for its likeliness to be faulty. The example in Fig. 2 shows the faulty statement is ranked in the fifth out of 25 based on the result of pair *f* and *g*. Based on this illustration of how Pair Scoring works for a pair of test case, we design a new SBFL metric which can be applied to a set of test cases by taking all possible combinations of pairing a past and a fail test cases based on the execution or non-execution of a statement and multiply it with the scores in Fig. 2.

Original version:

Simplified version:

For each statement, the total combination for a pass test case that has not executed the statement and a fail test case that has not executed the statement is *anp* multiplied by *anf* (*anp* x *anf*) and this is multiplied with zero as such pair of test cases are assigned a score of zero. This forms the first term of Equation (2) in Fig. 3. Similarly, for the second term of Equation (2), there are (*anp* x *aef*) combinations for pairs of a pass test case that has not executed the statement with a fail test case that has executed the statement. This is multiplied with two as such pair of test cases is assigned a score for high risk of two as shown in Fig. 2. The complete formula for this new "pair scoring" SBFL metric is shown in equation (2) below. This equation can be further simplified to equation (3).

IV. EXPERIMENT

In order to evaluate the performance of the proposed pair scoring SBFL metric, experiments have been conducted to apply this new technique to locate faults in faulty versions of programs in Siemen Test Suite. As discussed in Section II, the percentage of code inspected (*pci*) before the faulty statement is successfully located is used to measure the performance of this SBFL metric. For each program in Siemen Test Suite, we averaged the *pci* results of all faulty versions for that program. The results of the experiments are shown in Table III for *print_token*, *print_token2*, *replace* and Table IV for *schedule*, *schedule2*, *tcas* and *tot_info*. The average *pci* for all seven programs in Siemen Test Suite are presented in Table IV. The same experiment is repeated on 31 other existing SBFL metrics for performance comparison. *Journal of Industrial and Intelligent Information (i.e.,* December 2013)

Separation Vol. 1, This pair section Vol. 1, No. 4, December 2013

Concern in the latter of the number 2013

CFS 2 December 2013

CFS 2 December 2

V. DISCUSSION

Based on the results in Table III and Table IV, it can be observed that the proposed Pair Scoring approach outperformed majority of the 31 existing SBFL metrics. Overall, when the average performances over seven programs in Siemen Test Suites are taken into account, Pair Scoring outperformed 27 out of 31 (or 84.3%) of the existing SBFL metrics. Moreover, Pair Scoring is the best performing SBFL metric for two programs, namely, *print_tokens* and *replace*.

(3)

VI. CONCLUSION

In software development life cycle, software testing and debugging has been known as the most cost and time consuming activity. Spectrum-based Fault Localization (SBFL) technique has emerged as an effective solution to save the time and cost of the debugging process. SBFL metrics have been formulated to rank the statements in software code according to their likeliness to be the faulty statement. A good SBFL metric will rank faulty statement Although many SBFL metrics have been proposed, every SBFL metric is designed differently to rank the suspected statement. This makes every SBFL metric unique and has different capability in fault localization.

In this paper, we proposed a new SBFL metric named, Pair Scoring. This technique works by comparing the execution paths of a pair of pass and fail test cases and assign score to each statement according to its likeliness to be the faulty statement. All possible combinations of pass and fail test cases are paired for scoring and the total score for each statement is used to rank the statement for its likeliness to be faulty. We evaluated the performance of the proposed metric on real life software artifacts and compare it with other existing SBFL metrics. Despite its simplicity, we found the proposed metric outperformed majority of the existing SBFL metrics.

print tokens		print tokens2		replace			schedule	
SBFL Metrics	PCI							
Ample	0.36	Naish1	1.29	Naish2	2.40	M ₂	1.11	
M ₂	0.36	Naish2	1.29	Pair Scoring	2.40	Naish1	1.11	
Naish1	0.36	Zoltar	1.29	Zoltar	2.43	Naish2	1.11	
Naish2	0.36	Wong3	1.37	M ₂	2.43	Zoltar	1.11	
Ochiai	0.36	M ₂	2.80	Ochiai	2.66	Pair Scoring	1.21	
Pair Scoring	0.36	Pair Scoring	3.01	Geometric_Mean	2.92	Ochiai	1.35	
Wong3	0.36	Ochiai	4.68	Naish1	2.98	Anderberg	1.74	
Zoltar	0.36	Arithmetic Mean	6.62	Arithmetic Mean	2.99	Dice	1.74	
Arithmetic_Mean	0.41	Geometric Mean	6.69	Harmonic Mean	3.10	Jaccard	1.74	
Geometric_Mean	0.41	Harmonic Mean	7.12	Rogot2	3.10	Kulczynski1	1.74	
Ochiai2	0.41	Rogot2	7.12	Ochiai2	3.62	qe	1.74	
Harmonic Mean	1.01	Ample	7.87	Anderberg	3.89	Sorensen-Dice	1.74	
Rogot2	1.01	Anderberg	7.91	Dice	3.89	Tarantula	1.74	
Anderberg	1.48	Dice	7.91	Jaccard	3.89	Arithmetic Mean	8.04	
Dice	1.48	Jaccard	7.91	Kulczynski1	3.89	Geometric Mean	8.18	
Jaccard	1.48	Sorensen-Dice	7.91	Sorensen-Dice	3.89	Harmonic Mean	8.18	
Sorensen-Dice	1.48	Ochiai2	7.97	Cohen	4.08	Rogot2	8.18	
Cohen	2.25	CBI Inc.	8.08	CBI Inc.	4.10	CBI Inc.	8.57	
CBI_Inc.	2.55	Cohen	8.08	qe	4.10	Cohen	8.57	
qe	2.55	qe	8.08	Tarantula	4.10	Euclid	9.54	
Tarantula	2.55	Tarantula	8.08	Ample	4.89	Hamming etc.	9.54	
Euclid	5.68	AMPLE2	10.90	Wong3	6.26	M ₁	9.54	
Hamming_etc.	5.68	Binary	10.90	AMPLE ₂	6.44	Rogers&Tanimoto	9.54	
Rogers&Tanimoto	5.68	Russel & Rao	10.90	Russel & Rao	6.44	Simple_Matching	9.54	
Simple_Matching	5.68	Wong1	10.90	Wong1	6.44	Sokal	9.54	
Sokal	5.68	Euclid	11.70	Binary	7.02	AMPLE2	9.89	
AMPLE2	8.70	Hamming etc.	11.70	Euclid	15.04	Binary	9.89	
Binary	8.70	Rogers&Tanimoto	11.70	Hamming_etc.	15.04	Russel & Rao	9.89	
Russel & Rao	8.70	Simple_Matching	11.70	M1	15.04	Wong1	9.89	
Wong1	8.70	Sokal	11.70	Rogers&Tanimoto	15.04	Ochiai2	12.41	
Kulczynski1	22.20	Kulczynski1	24.30	Simple_Matching	15.04	Ample	17.68	
M1	26.94	M1	28.10	Sokal	15.04	Wong3	19.28	

TABLE III. AVERAGE SBFL METRIC PERFORMANCE

TABLE IV. AVERAGE SBFL METRIC PERFORMANCE

ACKNOWLEDGMENT

This work is supported via Malaysian Government MOHE Fundamental Research Grant Scheme (FRGS/2/2010/TK/SWIN/02/03).

REFERENCES

- [1] B. Hailpern and P. Santhanam, "Software debugging, testing, and verification," *IBM Systems Journal*, 2002, vol. 40, no1.
- [2] G. J. Myers, *The Art of Software Testing*, 2nd edn. John Wiley and Sons, Revised and updated by T.Badgett and T. M. Thomas with C. Sandler: Hoboken, 2004.
- [3] H.J. Lee, L. Naish, and K. Ramamohanarao, "A model for spectrabased software diagnosis," *ACM Transactions on Software Engineering and Methodology*, 2011, vol. 20, no. 3.
- [4] X.Y. Xie, T. Y. Chen, and B. W. Xu, "Isolating suspiciousness from spectrum-based fault localization techniques," in *Proc. 10th International Conference on Quality Software*, 2010, pp. 385–392.
- [5] X. Y. Xie, W .E. Wong, T. Y. Chen, and B. W. Xu, "Spectrum-Based fault localization: testing oracles are no longer mandatory, in *Proc. 11th International Conference on Quality Software*, 2011, pp. 1–10.
- [6] R. Abreu, P. Zoeteweij, and A. van Gemund, "On the accuracy of spectrum-based fault localization," *TAICPARTMUTATION*, 2007, pp. 89–98.
- [7] H. J. Lee, L. Naish, and K. Ramamohanarao, "The effectiveness of using non redundant test cases with program spectra for bug localization," in *Proc. 2nd IEEE international Conference, Computer Science and Information Technology,* 2009, pp. 127– 134. *Journal of Intelligent Information Company* \sim 190 **Journal of Intelligent Intelligent Information Vol. 1, No. 4, December 2013**

This work is supported via Malaysian Georgrandet III A. Really-publishes and the enginee
- [8] R. Abreu, P. Zoeteweij, and A. van Gemund, "An evaluation of similarity coefficients for software fault localization," in *Proc. 12th PRDC*, 2006, pp. 39–46.
- [9] C. Gong, Z. Zheng, W. Li, and P. Hao, "Effects of class imbalance in test suites: An empirical etudy of spectrum-based fault localization," in *Proc. IEEE 36th International Conference on Computer Software and Applications Workshops*, 2012, pp.470– 475.
- [10] R. Abreu, A. Gonzalez, P. Zoeteweij, and A. Van Gemund, "Automatic software fault localization using generic program invariants," in *Proc. SAC*, Brazil, 2008, pp. 712–717.
- [11] A. Bandyopadhyay, "Improving spectrum-based fault localization using proximity-based weighting of test cases," in *Proc. ASE*, USA, 2011, pp. 660–664.
- [12] A. Bandyopadhyay, "Mitigating the effect of coincidental correctness in spectrum based fault localization," in *Proc. IEEE 5th International Conference on Software Testing, Verification and Validation*, 2012, pp. 479–482.
- [13] H. Do, S. Elbaum, and G. Rothermel, "Supporting controlled experimentation with testing techniques: An infrastructure and its potential impact," *Empirical Software Engineering*, 2005, vol. 10, no. 4, pp. 405–435.
- [14] R. Abreu, W. Mayer, M. Stumptner and A. Van Gemund, "Refining spectrum-based fault localization rankings," in *Proc. SAC*, USA, 2009, pp.409–414.
- [15] R. Abreu, A. Gonzalez, and A. Van Gemund, "Exploiting count spectra for bayesian fault localization," in *Proc. PROMISE*, Romania, 2010, pp. 1–10.
- [16] A. Bandyopadhyay and S. Ghosh, "Proximity based weighting of test cases to improve spectrum based fault localization," in *Proc. ASE*, USA, 2011, pp. 420–423.

Patrick Daniel received his Bachelor of Science (CSSE) from Swinburne University of Technology in 2011. He is currently a Master of Science candidate at Swinburne University of Technology, Sarawak Campus, Malaysia. His research interest is software testing and debugging.

Kwan Yong Sim received his BEng (Hons) from the National University of Malaysia in 1999 and Masters of Computer Science from University of Malaya, Malaysia in 2001. He is currently a Senior Lecturer at the Faculty of Engineering, Computing and Science, Swinburne University of Technology, Sarawak Campus, Malaysia. His research interests are software testing and analysis.